

A REVIEW OF INTELLIGENT ROCK MECHANICS: FROM METHODS TO APPLICATIONS CONFERENCE SUBMISSIONS

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ABSTRACT

Intelligent rock mechanics represents the convergence of artificial intelligence (AI) and classical rock mechanics, providing new paradigms to understand, model, and predict the complex behaviors of geological materials. This review synthesizes recent progress from foundational AI methodologies to their practical applications in rock engineering. Traditional challenges—such as anisotropy, discontinuities, and multiphysics coupling—have been re-examined through data-driven and hybrid approaches that integrate learning algorithms with physical principles. The study traces the evolution of AI in this field, from early backpropagation and support vector machines to modern deep learning frameworks such as convolutional and transformer architectures, highlighting their roles in microstructure reconstruction, mechanical parameter estimation, constitutive modeling, and real-time hazard prediction. Emerging techniques, including physics-informed neural networks and graph-based learning, bridge data-driven inference with physical interpretability, while large language models are beginning to facilitate automated code generation and decision support in geotechnical analysis. Despite remarkable progress, key challenges remain in data quality, model generalization, and interpretability. Addressing these issues requires standardized datasets, interdisciplinary collaboration, and the establishment of transparent, reproducible AI workflows. The paper concludes by outlining a forward-looking perspective on developing next-generation intelligent frameworks capable of coupling physical knowledge, spatial reasoning, and adaptive learning, thereby advancing rock mechanics from empirical modeling toward fully intelligent, autonomous systems.

1 INTRODUCTION

Artificial Intelligence (AI) has evolved from an abstract computational theory into a transformative force reshaping scientific inquiry and engineering design across disciplines—including rock mechanics. The intellectual roots of AI trace back to the mathematical formalization of neural activity by McCulloch and Pitts in 1943 (McCulloch & Pitts, 1943), whose neuron model established the conceptual bridge between biological cognition and digital computation. The subsequent introduction of the backpropagation algorithm in 1986 (Rumelhart et al., 1986) revolutionized the training of multilayer neural networks and laid the groundwork for modern deep learning. By the early 1990s, researchers had begun applying these architectures to rock mechanics, where backpropagation networks were used to estimate elastic properties and optimize mining configurations (Zhang et al., 1991). The next three decades witnessed an explosion of model diversity, from convolutional neural networks (CNNs) (LeCun et al., 1989) and long short-term memory (LSTM) networks (Hochreiter & Schmidhuber, 1997) to generative adversarial networks (GANs) (Goodfellow et al., 2014) and attention-based transformers (Bahdanau et al., 2015; Vaswani et al., 2017). Each generation expanded the frontier of AI applications—CNNs improved microseismic event localization in underground mines (Huang et al., 2018), LSTMs modeled rheological behavior from early deformation histories (Qi & Fourie, 2018), and GANs synthesized realistic seismic waveforms (Wang et al., 2021). Transformers, originating in natural language processing, have now been adapted for visual classification tasks such as identifying rock fragments from post-blasting imagery (Li et al.,

2025). Together, these developments reflect a long trajectory of conceptual transfer, in which core AI architectures progressively migrated from cognitive science to computational geomechanics.

A bibliometric overview based on 17 leading journals in rock mechanics and related engineering disciplines was conducted to capture the diffusion of AI methodologies across the field. The survey covered journals such as *International Journal of Rock Mechanics and Mining Sciences*, *Engineering Geology*, *Computers and Geotechnics*, and *Tunnelling and Underground Space Technology*, among others, representing the major publication venues for both theoretical and applied geomechanics. Using “artificial intelligence,” “machine learning,” “deep learning,” and “data-driven modeling” as core search terms, all articles published before 2025 were systematically retrieved and filtered to ensure relevance to AI-assisted rock or geotechnical modeling. The retrieved corpus was then analyzed for publication trends, keyword co-occurrence, and methodological focus to establish the thematic landscape of AI adoption. The results highlight that AI has taken root most strongly in computational mechanics, owing to its reliance on mathematical abstraction and algorithmic optimization. Yet, compared with other branches of civil or mechanical engineering, the research volume in rock mechanics remains modest—reflecting both the difficulty of obtaining high-quality subsurface data and the still-emerging stage of methodological adaptation. Nevertheless, the keyword network analysis reveals a clear conceptual transition: the term “machine learning” now surpasses “artificial intelligence” in frequency, signaling a shift toward data-driven modeling paradigms. Among these approaches, support vector machines (SVMs) (Vapnik & Chervonenkis, 1964) first gained prominence through kernel-based nonlinear classification (Cortes & Vapnik, 1995), bridging traditional statistical learning and modern deep architectures. More recent research extends this trajectory toward physics-informed neural networks (PINNs) (Abueidda et al., 2021), which embed governing physical laws directly into loss functions, aligning data-driven inference with mechanical consistency. The growing adoption of such hybrid models underscores a collective movement within geomechanics toward interpretability, robustness, and scientific grounding—attributes once viewed as beyond the scope of purely data-driven AI.

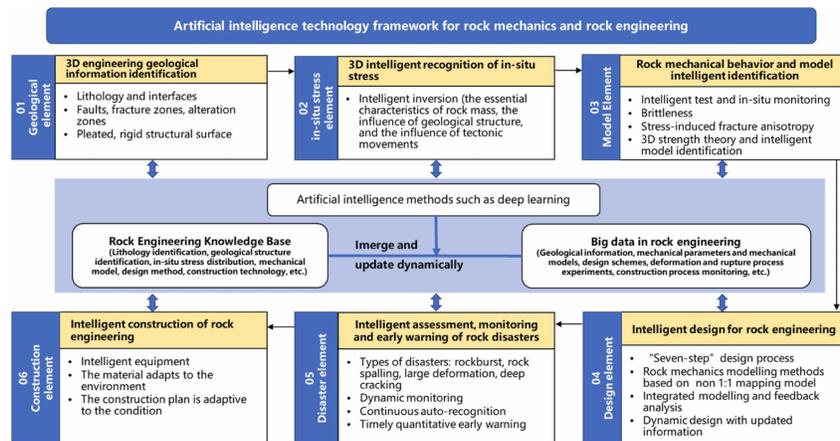


Figure 1: Systematic composition of rock mechanics and engineering in the view of the metaverse under the backdrop of artificial intelligence technology (Feng et al., 2024).

The integration of AI into rock mechanics, however, is far from a simple transplantation of algorithms (as shown in Figure 1). Rocks differ fundamentally from continuum materials in their heterogeneity, anisotropy, and multi-scale discontinuities—ranging from microcracks to regional fault systems. These features, coupled with strong nonlinearity, rate dependence, and multiphysics coupling, create modeling barriers that classical continuum mechanics alone cannot resolve. In this context, AI provides new tools for addressing long-standing challenges: inferring mechanical parameters from sparse data, reconstructing microstructures, identifying joint networks, and forecasting instability phenomena such as rock bursts. Yet, the field still faces limitations rooted in data scarcity, measurement uncertainty, and the difficulty of assembling large, high-quality datasets for model training and validation. As this review aims to synthesize, AI’s evolution—from the McCulloch-Pitts neuron to modern transformer-based architectures—has progressively reshaped the analytical landscape of rock mechanics. Grounded in the conceptual legacy of the Turing Test (Turing, 1950),

108 a framework is proposed to categorize AI in this field according to its cognitive resemblance and
109 level of abstraction. By bridging theoretical advances with engineering practice, AI not only aug-
110 ments the predictive capacity of rock mechanics but also redefines its epistemology—transforming
111 it from a purely empirical discipline into a data-driven, intelligence-enabled science poised for the
112 next generation of discovery.

113 114 115 2 DATA-DRIVEN ESTIMATION OF ROCK PROPERTIES 116 117

118 In recent years, the estimation of rock mechanical properties has undergone a paradigm shift from
119 traditional empirical correlations toward data-driven learning frameworks. Instead of relying solely
120 on direct laboratory measurements, researchers have increasingly exploited the predictive capac-
121 ity of machine learning to infer rock strength and stiffness from easily obtainable indirect indica-
122 tors. Early studies demonstrated that artificial neural networks (ANNs), particularly those based on
123 backpropagation (BP), could effectively capture the nonlinear relationship between uniaxial com-
124 pressive strength (UCS) and parameters such as P-wave velocity, rebound number, or point-load
125 index, using datasets like the 108-sample sandstone collection from the Dengkil site in Malaysia
126 [28]. Although BP networks offer transparent and flexible implementations, their performance re-
127 mains sensitive to data completeness and noise. To address these limitations, a suite of advanced
128 algorithms—including adaptive neuro-fuzzy inference systems (ANFIS) (Yesiloglu-Gultekin et al.,
129 2013), support vector machines (SVM) (Ceryan et al., 2013), extreme learning machines (ELM)
130 (Liu et al., 2015), and regression trees (Tiryaki, 2008)—has been introduced. SVMs provide robust
131 generalization in small datasets through kernel mapping, while ANFIS models integrate fuzzy logic
132 to accommodate uncertainty in geological parameters such as porosity or density. Literature-derived
133 databases have further expanded the scope of predictive modeling. Studies compiling 199–367
134 records from diverse rock types have yielded ANN and soft computing models capable of estimating
135 UCS and other strength parameters, including triaxial and shear strength (Skentou et al., 2023; Le
136 et al., 2022). Beyond intact rocks, data-driven frameworks have also been applied to rock-mass char-
137 acterization using empirical descriptors (e.g., RMR class, Q-value, or UCS of intact rock) (Miranda
138 et al., 2010), and to drilling data analysis through physics-informed convolutional neural networks
139 that relate thrust force, torque, and penetration rate to UCS in jointed rock masses (He et al., 2021).
140 Similar strategies have been extended to engineered geomaterials such as geopolymer-stabilized or
141 cement-treated soils, demonstrating the general applicability of these methods to complex heteroge-
142 neous media (Mozumder & Laskar, 2015; Narendra et al., 2006).

142 Parallel advances have been achieved in predicting elastic moduli through hybrid data–model inte-
143 gration. Neural networks with multi-output architectures have been trained to simultaneously esti-
144 mate UCS and Young’s modulus by extending the output layer (Yagiz et al., 2012), while numerical
145 databases derived from microstructural simulations have provided valuable synthetic training data.
146 For example, fast Fourier transform–based models of the interface transition zone (ITZ) have been
147 used to generate elastic property datasets for heterogeneous materials, subsequently mapped using
148 multilayer BP networks (Xue et al., 2023). Hybrid learning schemes such as ANFIS have been
149 applied to infer dynamic elastic moduli of thermally damaged rocks from UCS and Brazilian ten-
150 sile strength (Waqas & Ahmed, 2020), and ensemble models such as random forest, AdaBoost,
151 extreme gradient boosting, and CatBoost have shown excellent capability in predicting moduli of
152 weak sedimentary rocks based on porosity, density, and durability data (Abdi et al., 2023). Mul-
153 tivariate regressors have also revealed the compositional dependence of granite stiffness on quartz
154 and feldspar contents, as well as dry density and sonic velocity (Jahed Armaghani et al., 2015).
155 Additional progress includes ANN-based correlations between P-wave velocity and field test in-
156 dices (Behzadafshar et al., 2019), Bayesian frameworks that quantify prediction uncertainty for
157 elastic constants (Feng & Jimenez, 2014), and neural-network-assisted finite element models capa-
158 ble of recovering the five elastic constants of transversely isotropic rocks from limited experimental
159 orientations (Lee et al., 2022). Extending beyond rocks, support vector regression and Gaussian
160 process regression models have been effectively used to estimate the resilient modulus of treated
161 subgrade and clay soils from material and additive features, with polynomial kernels often outper-
forming RBF and linear ones (Heidaripناه et al., 2017; Hu & Solanki, 2021). Together, these
developments highlight the ability of data-driven approaches to unify static and dynamic elasticity
estimation under a consistent computational paradigm.

Beyond strength and stiffness, machine learning has also transformed the estimation of wave velocities and other geomechanical attributes. Recent studies have integrated artificial neural networks, fuzzy systems, and evolutionary optimization into hybrid architectures that predict sonic velocities from well-log data, achieving high accuracy on over 1,600 records from the Asmari formation through committee-based learning with weighted fusion (Asoodeh & Bagheripour, 2012). Physics-guided neural networks have further advanced velocity inversion by incorporating frequency-domain constraints into loss functions, ensuring physical plausibility and improved well-posedness of shear-wave velocity profiles from downhole signals (Ji et al., 2025). Similarly, convolutional regression models leveraging transfer learning can infer compressional velocities directly from core sample images of cement-reinforced soils, establishing a bridge between visual and mechanical domains (Kim et al., 2023). Ensemble-based architectures, such as VelProfES, combine real and synthetically generated borelog datasets—enhanced by conditional generative adversarial networks (CT-GANs)—to predict shear-wave velocity profiles across more than 10,000 synthetic and real stations (Joshi et al., 2024). The same methodological foundation has been adapted to infer diverse rock and soil properties, including fracture toughness (Afrasiabian & Eftekhari, 2022), soil-water characteristic curves (Li & Vanapalli, 2022), Poisson’s ratio (Alakbari et al., 2024), and permeability (Kayabasi et al., 2015). Collectively, these studies illustrate a growing trend toward physics-aware, data-driven frameworks that enable multi-property estimation across scales—offering a coherent pathway for intelligent characterization and prediction of rock mechanical behavior from heterogeneous data sources.

3 IMAGE-BASED MODELING AND FRACTURE DETECTION

The geometric complexity of rock microstructures and discontinuities has long been recognized as one of the fundamental barriers to accurate mechanical modeling. Many macroscopic behaviors—such as rate-dependent strength or nonlinear deformation—originate from processes occurring at the grain or pore scale. To overcome the limitations of traditional imaging and reconstruction approaches, recent research has increasingly adopted image-based and data-driven frameworks to recover the internal geometry of rocks from limited or indirect observations. Early numerical approaches employed simulated annealing (SA) optimization to generate three-dimensional digital rocks from limited surface or section images, reproducing statistical features of microstructures without requiring extensive datasets (Yin & Zhao, 2014; Wei et al., 2023). Although this method provided an elegant solution for small-sample reconstruction, it was hindered by heavy computational cost and low scalability when dealing with complex multiphase materials. The advent of deep learning revolutionized this domain by enabling direct 3D reconstruction from 2D imagery. Neural network-based frameworks now learn mappings between image features and volumetric structures, achieving orders-of-magnitude speedups over SA methods while retaining statistical realism (Feng et al., 2020). Generative models have further extended this paradigm: variational autoencoders (VAEs) have been trained on micro-CT datasets containing tens of thousands of sand particles to generate realistic particle geometries for discrete element modeling (Feng et al., 2020), and voxel-based 3D generative adversarial networks (GANs) have been developed to synthesize large-scale multiphase structures with anisotropic or frozen granular components (Argilaga et al., 2024). More recently, image enhancement networks such as DeblurGAN have been applied to reconstruct true-color 3D granite textures from sequential rock surface images, demonstrating the potential of combining physical imaging and data-driven restoration for microstructural realism (Zhao et al., 2025). These methods collectively signal a transition from purely statistical reconstructions toward AI-driven volumetric modeling capable of capturing the inherent heterogeneity of geomaterials.

Parallel to microstructural reconstruction, AI has become an essential tool for image-based fracture detection and geometric extraction at both laboratory and field scales. Convolutional neural networks (CNNs) have been extensively used to automate the segmentation and quantification of rock fractures, outperforming conventional image-processing pipelines in accuracy and noise suppression. The FraSegNet architecture, for example, was trained on thousands of tunnel fracture images and achieved superior fracture trace extraction performance across variable lighting and texture conditions (Chen et al., 2021). Similar CNN variants such as DeepLab V3+ and UNet3+ have been applied to high-resolution CT imagery of igneous rocks, providing microscale crack segmentation at submicron accuracy (Lei & Fan, 2024). Despite these advances, CNN-based models still suffer from limited robustness when faced with low contrast, irregular morphologies, or imbalanced datasets. Beyond 2D imagery, 3D point-cloud-based approaches have emerged as a promising al-

216 alternative. Ensemble learning frameworks integrating support vector machines and random forests
217 have been developed to identify discontinuities in laser-scanned tunnel faces, even when the sur-
218 faces were obscured by shotcrete or excavation artifacts (Peng et al., 2024). Such models achieve
219 strong generalization by aggregating predictions from multiple learners, though they require sub-
220 stantial feature engineering and computational resources. The integration of transfer learning has
221 further enhanced the adaptability of deep segmentation networks to small, domain-specific datasets,
222 enabling stable fracture extraction and 3D reconstruction across different rock types (Pan et al.,
223 2024). Nonetheless, the accurate restoration of the spatial topology of fracture networks remains
224 challenging and continues to motivate research into multi-view and multimodal fusion methods.

225 Recent progress in combining deterministic and stochastic modeling frameworks has further im-
226 proved the structural interpretation of discontinuities from image and point-cloud data. The De-
227 terministic–Stochastic Identification and Modelling (DSIM) method represents one such approach,
228 where discontinuity features—such as joint orientation and aperture—are statistically characterized
229 through hybrid region-growing and Gaussian fitting strategies applied to outcrop-scale datasets (Pan
230 et al., 2019). By integrating visual and geometric cues from both real imagery and 3D point clouds,
231 DSIM effectively reduces uncertainty in discrete fracture network (DFN) modeling and has been
232 successfully validated through field applications, such as the Heijing Limestone Mine in Guangxi,
233 China. Together, these advances reflect a broader methodological convergence in rock mechanics:
234 the fusion of imaging technologies, deep generative models, and hybrid statistical–deterministic
235 analysis now enables more precise reconstruction and detection of fractures across scales. This
236 image-driven perspective not only enhances our ability to simulate the mechanical response of dis-
237 continuous rock systems but also lays the groundwork for a new generation of digital twin frame-
238 works in geomechanics—where reconstruction, detection, and prediction are integrated within uni-
239 fied AI-based modeling pipelines.

240 4 AI-ASSISTED CONSTITUTIVE MODELING AND SIMULATION

241 The development of artificial intelligence has opened a new paradigm for constitutive modeling in
242 rock mechanics, shifting from empirically defined constitutive laws to data-driven and self-adaptive
243 formulations. Early studies demonstrated that backpropagation (BP) neural networks could approxi-
244 mate complex rock strength criteria through direct learning from experimental databases rather than
245 relying on predefined yield functions (Rafiai & Jafari, 2011; Rafiai et al., 2013). These models were
246 trained on extensive polyaxial test datasets covering multiple rock types, allowing nonlinear failure
247 envelopes to emerge automatically from data correlations. Beyond BP networks, ensemble and prob-
248 abilistic regressors such as Gaussian process regression, random tree, and M5P models have been
249 used to construct interpretable and uncertainty-aware strength criteria from multi-source datasets
250 (Fathipour-Azar, 2023). More recently, sequential neural architectures—such as long short-term
251 memory (LSTM) networks—have gained attention for capturing history-dependent constitutive re-
252 sponses. LSTM-based frameworks have been successfully employed to simulate stress–strain evolu-
253 tion in soils and other path-dependent materials (Zhang et al., 2023a; Bahtiri et al., 2023), as well as
254 to reproduce cyclic viscoelastic–viscoplastic behaviors in heterogeneous composites. Hybrid deep
255 models combining LSTM with temporal convolutional networks (TCN) have further demonstrated
256 the ability to learn both monotonic and cyclic deformation mechanisms from limited data (Guan
257 & Yang, 2023). These AI-driven constitutive models, once integrated into finite element solvers,
258 effectively replace conventional empirical formulations and allow continuum-scale simulations to
259 inherit the nonlinear, multiaxial, and rate-dependent behavior observed in laboratory tests.

260 Parallel progress has been achieved in embedding AI directly into the numerical solution of gov-
261 erning equations. Traditional partial differential equations describing elasticity, diffusion, and mul-
262 tiphysics coupling have been reformulated through machine learning surrogates that blend physical
263 constraints with data-driven inference. BP neural networks have been inserted at Gauss integra-
264 tion points within finite element meshes to emulate representative volume elements (RVE) derived
265 from discrete element simulations, enabling a hybrid FEM–DEM framework capable of resolv-
266 ing anisotropy and microscale interactions in granular materials (Guan et al., 2024). Building
267 on this concept, physics-informed neural networks (PINNs) emerged as a general framework for
268 solving nonlinear PDEs by incorporating governing equations into loss functions. However, chal-
269 lenges in convergence and stability have led to refined architectures such as the physics-informed
radial basis network (PIRBN), which introduces localized basis functions to better capture diffu-

270 sion and viscoelastic flow behavior (Bai et al., 2023a). Similarly, the physics-informed temporal
271 convolutional network (PI-TCN) has been integrated with variational formulations of finite element
272 analysis to efficiently simulate transient thermoelastic problems while reducing differentiability and
273 memory constraints (Abueidda & Mobasher, 2024). These methods have also been extended to
274 poromechanical systems, addressing coupled flow–deformation equations for both single- and mul-
275 tiphase media through dimensionless reformulation and stress-split training schemes that stabilize
276 optimization (Haghighat et al., 2022). In addition to PINN variants, alternative architectures such
277 as multi-fidelity graph neural networks (MFGNNs) (Black & Najafi, 2022), recurrent networks
278 (RNNs, LSTMs, GRUs) (Hu et al., 2022), and convolutional-peridynamic hybrids (Mavi et al.,
279 2023) have been explored for solving elasticity, phase-field, and nonlocal fracture problems with
280 improved accuracy–efficiency trade-offs.

281 Collectively, these developments mark a convergence between machine learning and computational
282 mechanics, where AI serves not merely as a surrogate but as an active component of the constitu-
283 tive and governing framework. By coupling data-driven learning with physical priors, AI-assisted
284 models can reveal hidden structure–property relationships that transcend empirical formulations and
285 extend predictive capability across scales—from grain-level anisotropy to continuum-scale deforma-
286 tion. Yet, the application of such techniques in rock mechanics remains nascent compared to other
287 material domains. Future research will likely emphasize hybrid physics–data architectures, multi-
288 scale transfer learning, and uncertainty quantification, integrating neural constitutive laws with nu-
289 merical solvers to form self-evolving simulation systems. These intelligent frameworks have the po-
290 tential not only to reproduce observed mechanical responses but also to uncover emergent behaviors,
291 offering a pathway toward autonomous, knowledge-guided constitutive modeling and simulation in
292 rock and geomaterial mechanics.

293 5 APPLICATIONS IN ROCK ENGINEERING

294 The ultimate value of intelligent rock mechanics lies in solving real-world engineering problems
295 more effectively than before. Across various sub-disciplines of rock engineering, AI and ML tech-
296 niques have begun to yield tangible improvements in analysis, design, and decision-making. Here
297 we survey several key application areas where these intelligent methods are making a difference.
298
299

300 5.1 ROCK MASS CLASSIFICATION AND CHARACTERIZATION

301 Rock mass classification plays a foundational role in the design and stability assessment of tunnels,
302 slopes, and other rock engineering projects, yet traditional systems such as RMR and Q remain
303 constrained by empirical formulations and regional calibration, often requiring expert judgment for
304 parameter interpretation. Artificial intelligence (AI) introduces a paradigm shift in this field by
305 enabling data-driven classification and automated feature extraction that transcend site-specific em-
306 pirical dependence. Recent reviews have summarized substantial progress in AI-powered method-
307 ologies for rock mass evaluation (Saadati et al., 2024), where machine learning models are em-
308 ployed to infer classification indices directly from measurable or visual inputs. For example, hybrid
309 frameworks combining support vector classification (SVC) and backpropagation neural networks
310 (BPNN) have been trained on multi-site tunnel databases to refine basic quality (BQ) predictions,
311 with SVC outperforming BPNN due to its superior capability to identify nonlinear decision bound-
312 aries in heterogeneous geological data (Liu et al., 2019). Similarly, regression-based algorithms
313 such as relevance vector regression (RVR) and support vector regression (SVR) have demonstrated
314 significant improvements in estimating Rock Mass Rating (RMR) values compared to conventional
315 empirical conversions, reducing systematic over- and underestimation errors through probabilis-
316 tic inference (Gholami et al., 2013). AI also enables a transition from manual to image-based
317 rock mass characterization: neural networks can derive the Geological Strength Index (GSI) from
318 three-dimensional point cloud data captured via photogrammetry or unmanned aerial vehicle (UAV)
319 surveys, automatically quantifying geometrical attributes such as trace length, orientation density,
320 and intersection frequency (Zeni et al., 2021). Convolutional neural networks (CNNs) extend this
321 capacity by directly learning visual patterns from thousands of core images, achieving high accu-
322 racy in predicting Rock Quality Designation (RQD) across lithologies while eliminating the need
323 for manual labeling (Alzubaidi et al., 2022). Moreover, hybrid neuro-fuzzy systems such as the
Adaptive Neuro-Fuzzy Inference System (ANFIS) have integrated mechanical and geological in-

dicators—uniaxial compressive strength (UCS), RQD, joint spacing (JS), joint condition (JC), and groundwater (GW)—to estimate RMR in diverse field environments, combining the interpretability of fuzzy logic with the adaptivity of neural learning (Jalalifar et al., 2011). Collectively, these AI-based approaches transform rock mass classification from an experience-dependent process into a quantitative, reproducible, and scalable framework, capable of integrating image analysis, field sensing, and machine learning to deliver consistent, objective, and high-resolution characterization of geological materials.

5.2 ROCKBURST AND GEOHAZARD PREDICTION

Rockburst represents one of the most complex and hazardous manifestations of rock mass instability, where the abrupt release of stored elastic energy under high stress leads to violent ejection and catastrophic damage in deep tunnels, mines, and hydropower caverns. The nonlinear coupling among geological heterogeneity, in-situ stress distribution, and excavation-induced perturbations makes its prediction extremely challenging for conventional empirical or analytical models. Artificial intelligence (AI) has therefore emerged as a transformative tool for rockburst and geohazard prediction, providing a data-driven framework capable of learning the intrinsic relationships between precursor signals and failure intensity. Early AI applications employed fuzzy inference systems (FIS) to manage uncertainty and incomplete knowledge in geological datasets, yet their predictive capacity remained limited, as shown by (Adoko et al., 2013), whose model explained only 45.8% of the variance. By integrating neural learning, the adaptive neuro-fuzzy inference system (ANFIS) achieved substantial improvements, with 95.6% successful prediction accuracy and reduced error metrics, demonstrating the potential of hybrid logic-learning architectures in handling nonlinearity and fuzziness. Support vector machines (SVMs), often combined with regression splines or deep ensemble algorithms, have proven effective in modeling high-dimensional rockburst parameters, enabling multivariate decision boundaries that improve classification robustness (Guo et al., 2022). Neural networks—ranging from feedforward and convolutional (CNN) to extreme learning machines (ELMs)—have been extensively applied to identify rockburst precursors from monitoring data such as microseismic activity, stress ratios, or acoustic emissions, often enhanced through optimization strategies like particle swarm algorithms (Xue et al., 2020; Zhang et al., 2021). Ensemble learning methods further elevate prediction stability and precision: (Jia et al., 2024) demonstrated that integrating seven classifiers in a voting-ensemble framework increased accuracy by 4.4%, while (Liang et al., 2021) showed that multi-learner ensembles combining SVMs, logistic regression, and decision trees outperform individual models across precision and recall metrics. For time-dependent hazard forecasting, deep recurrent architectures—particularly long short-term memory (LSTM) networks—enable dynamic early-warning models that capture temporal dependencies in microseismic or stress evolution data. Hu et al. (Hu et al., 2023b) established an LSTM-based framework that predicted rockburst intensity and timing across blasting cycles with accuracies exceeding 70%, marking a key step toward continuous temporal risk monitoring. The reliability of these AI systems relies heavily on robust datasets integrating geological, geomechanical, and microseismic indicators, such as maximum tangential stress, uniaxial compressive strength, brittleness index, elastic energy, and event frequency. Effective preprocessing—including noise filtering, missing-value imputation, and class-balancing—is crucial; for instance, (Liu et al., 2023) employed K-means-based synthetic minority oversampling (KM-SMOTE) to mitigate imbalance in rockburst datasets, significantly enhancing predictive performance. Cross-validation procedures, such as k-fold optimization, ensure model generalization, as shown by (Zhang et al., 2020), who achieved over 15% improvement in accuracy after hyperparameter tuning. Collectively, these advancements demonstrate that AI has transcended empirical prediction, establishing an intelligent, adaptive, and interpretable framework for rockburst and geohazard forecasting—one capable of fusing multi-source data, uncovering latent physical patterns, and supporting real-time early warning in complex underground environments.

5.3 TUNNELING AND BORING OPERATIONS

Within the operational context of tunneling and boring, AI/ML has evolved from post-hoc curve fitting to an integrated decision engine that links geodata ingestion, physics-aware representation, and real-time control of construction variables in rock mechanics. Classic supervised learners remain valuable when aligned with mechanistic priors: multi-layer backpropagation networks map geometry-soil/rock-method descriptors to settlement metrics for construction planning and monitoring (Neaupane & Adhikari, 2006), and when trained on numerical experiments they can invert rheolog-

ical parameters in soft rock so that calibrated long-horizon deformation forecasts feed maintenance scheduling and support retuning (Kovacevic et al., 2021); replacing sigmoids with wavelet activations, Wavenet improves learning efficiency and generalization for maximum ground-surface settlement estimation during advance, making it attractive for data streams with nonstationary spectral content (Pourtaghi & Lotfollahi-Yaghin, 2012). Hybridizing data-driven inference with structural geology, a Gray BP framework coupled to a DFN uncovers a linear link between P-wave velocity and structural plane density, enabling data-assisted optimization of prestressed anchor layouts while revealing burial depth and cable length as primary drivers of surrounding-rock response (Li et al., 2023). For squeezing risk under weak or highly stressed rock, meta-heuristic optimization and probabilistic learning complement deterministic heuristics: a WOA-tuned SVM leverages multi-site case histories to classify squeezing from depth, stiffness, RTQI, diameter and strain inputs (Zhou et al., 2022), whereas a Naïve Bayes formulation provides robust prediction with incomplete evidence and low error across 10-fold validations and external cases (Feng & Jimenez, 2015). Ensemble and time-series architectures strengthen proactive control at the face: PSO-optimized XGBoost scores deformation risk in fault-fractured zones to prioritize countermeasures (Bo et al., 2024), and adaptive chaotic sparrow-search-enhanced ELM/AMLSTM pipelines anticipate short-term deformation trajectories for construction pacing and support staging (Dong et al., 2024). Blending physics constraints with data yields further gains in data-scarce, noisy settings critical to subsurface operations: a DPNN jointly infers geological parameters and ground-loss while outperforming SVM/BP under 20% noise, thus stabilizing settlement and volume-loss estimates needed for shield guidance and risk buffers (Liu et al., 2024); more generally, PINN formulations embed equilibrium and compatibility into displacement-field learning for shield tunneling, curbing extrapolation error and improving interpretability for engineers (Zhang et al., 2023b). Finally, sequence models close the loop on machine-ground interaction in EPB operations: LSTM predictors maintain posture accuracy and anomaly sensitivity despite delayed events and disturbances, outperforming ML ensembles and supporting on-the-fly set-point adjustments for torque, thrust, and chamber pressure (Bai et al., 2023b). Collectively, these advances position AI not as a black box but as a physics-constrained, data-efficient co-pilot for tunneling and boring operations—transforming rock-mechanics inference into actionable control for design, construction, and lifecycle risk management.

5.4 SLOPE STABILITY ANALYSIS

Framed within slope stability analysis and geomechanical hazard management, recent AI advances have shifted from ad-hoc predictors to rigorously validated surrogates and physics-aware learners that compress computational cost while preserving reliability: back-propagation neural networks and support vector machines accelerate Monte Carlo reliability by orders of magnitude with sub-percent bias, enabling probabilistic assessment under heterogeneity and anisotropy using only sparse training subsets (Aminpour et al., 2023a;b); data-centric toolchains extend to 3D effects through efficient ANN implementations (Meng et al., 2021) and to more interpretable and robust surrogates via monotonicity constraints and augmentation strategies that enforce geotechnical priors (Pei & Qiu, 2024). Classic BP paradigms have also been embedded in landslide hazard formulations—either coupled with interaction matrix theory (Ferentinou & Sakellariou, 2007) or distilled into open-pit operational indices such as the MSII for mine slopes (Zare Naghadehi et al., 2013) while deep learning fused with GIS and pseudo-static analyses yields high-fidelity susceptibility mapping at territory scale (Pradhan & Kim, 2021). Convolutional architectures further streamline mechanics-based workflows: pre-trained CNNs deliver near-instant estimates of safety factors and slip-surface geometry for design screening (Hsiao et al., 2022); CNN-enabled nonintrusive SRFEM resolves random-field variability without succumbing to dimensionality growth (Liu et al., 2023); and CNN meta-models substitute for random-field FEM in reliability calculations with superior accuracy–efficiency trade-offs (Wang et al., 2021). For forecasting, spatiotemporal CNN pipelines outperform rainfall-landslide correlations in operational nowcasting of engineered slopes (Xiao et al., 2022), and disciplined augmentation helps control overfitting on limited labeled cases (Soranzo et al., 2023). Beyond ANNs, kernel and gradient-boosting surrogates support scenario-specific risk evaluation: SVR/XGBoost frameworks quantify failure probability of reservoir slopes under rapid drawdown by ingesting geomechanical descriptors (Guardiani et al., 2022); rare-event seismic reliability is tractably resolved by marrying subset simulation with SVM classifiers in a collaborative conditioning scheme (Xu et al., 2023); and learning systems based on XGBoost (leveraging NGA-West2), subset simulation, K-fold validation, RVM-FORM hybrids, and related boosters provide competitive estimates of rainfall-induced failure probabilities while retaining statistical rigor (Li et al., 2017;

432 Wang et al., 2020; Świtajła et al., 2023). At the interface of deterministic modeling and statistical
433 learning, an uncoupled FEM–LEM pipeline supplies numerical labels to calibrate a random-forest
434 surrogate that classifies reservoir-slope responses with probabilistic consistency (Li & Vanapalli,
435 2022). Finally, hybrid ensembles consolidate complementary inductive biases from multiple learn-
436 ers: meta-stacking with bio-inspired search identifies performant base/meta-classifiers from FEA-
437 generated training corpora and generalizes to field cases with strong AUC while quantifying variable
438 importance (Kardani et al., 2021); genetic-algorithm–tuned mixtures of Gaussian processes, SVMs,
439 and boosted trees achieve further gains under cross-validation (Qi & Fourie, 2018); stacked ensem-
440 bles spanning AdaBoost/GBM families highlight the primacy of material parameters in predictive
441 stability (Lin et al., 2022); and combined RF–XGBoost models surpass SVM/logistic baselines
442 in regional landslide catalogs while ranking profile geometry among the dominant controls (Zhang
443 et al., 2022). Collectively, these contributions delineate an AI-enabled slope engineering workflow in
444 which data-efficient surrogates, physics-informed learning, and ensemble uncertainty quantification
445 cohere into fast, scalable, and decision-relevant tools for design screening, reliability assessment,
446 and operational forecasting across the rock-mechanics spectrum.

447 5.5 OTHER EMERGING APPLICATIONS

448

449 Positioned within rock mechanics and adjacent geotechnical practice, recent studies exemplify how
450 AI serves as a surrogate, predictor, and design aide across load-carrying assessment, ground response
451 forecasting, support optimization, and seismic detailing: trained on FLAC simulations governed by
452 the Hoek–Brown criterion, an ANN replaces cumbersome empirical or fully numerical workflows
453 to estimate shallow-foundation bearing capacity on rock masses using compact descriptors such as
454 lithology and uniaxial compressive strength, reproducing numerical trends with far lower computa-
455 tional burden (Millán et al., 2021); spatiotemporal sequence modeling further elevates predictive
456 fidelity for metro excavation environments, where a convolutional–recurrent hybrid (STdeep) cap-
457 tures spatial gradients and temporal memory in settlement records to yield stable, high-accuracy
458 forecasts for foundation-pit influence zones (Zhang et al., 2024); in support design for soft-rock
459 tunnels, a BP-driven dynamic framework couples with numerical simulations to tune active–passive
460 support parameters under evolving ground conditions (Liu et al., 2025), while an expanded op-
461 timization scheme that integrates P-wave velocity and geological context with a neural surrogate
462 isolates structural plane density and anchor cable length—together with burial depth—as dominant
463 drivers of surrounding-rock deformation, thereby sharpening design targets and improving deploy-
464 ment efficiency (Li et al., 2023); and for fault-crossing bridges, explainable ML pipelines trained
465 on large synthetic–empirical databases deliver rapid seismic classification/regression tools to size
466 cable restrainers, yielding transparent formulae suitable for preliminary and parametric design loops
467 (Zhang et al., 2024). Collectively, these AI instruments demonstrate tangible gains in efficiency
468 and accuracy across the rock-mechanics workflow; nevertheless, truly mature, field-proven, and
469 routinely adopted AI applications in rock engineering remain relatively scarce, underscoring the
470 need for physics-aware generalization, uncertainty quantification, and standardized validation be-
471 fore widespread practice integration.

472 6 CHALLENGES AND FUTURE DISCUSSIONS

473

474 Despite the impressive progress in intelligent rock mechanics, several challenges must be addressed
475 for these technologies to reach their full potential in practice:

476 **Data Limitations:** High-quality, representative data are the fuel for AI models, yet in rock mechanics
477 such data can be scarce or hard to share (see Appendix A.1). Many AI models discussed are trained
478 on relatively small datasets or data from specific sites, which raises concerns about overfitting and
479 generalizability. A concerted effort is needed to develop open, standardized databases for rock
480 mechanical properties, case histories, and monitoring data (Xiao et al., 2022). Collaborative data
481 repositories and industry-academia partnerships could help accumulate the large datasets necessary
482 for robust model training and validation. Additionally, methods to augment data – such as using
483 physics-based simulations or generative networks to create plausible synthetic data – will be valuable
484 in overcoming data scarcity.

485 **Model Interpretability and Trust:** Engineering fields demand that models not only perform well,
but also be interpretable and trustworthy for high-consequence decisions. Many AI models (e.g.

486 deep neural networks) are often criticized as "black boxes." Improving interpretability is thus a key
487 frontier. This could involve using simpler surrogate models to approximate the behavior of complex
488 networks or integrating explainable AI techniques that highlight which input features most influence
489 the predictions (for instance, identifying which combination of joint orientation and strength led
490 an ML model to flag a slope as unstable). The development of models that incorporate physical
491 laws (such as PINNs or hybrid models) is another way to boost trust, since they are constrained by
492 known behavior and less likely to predict nonsensical outcomes (Soranzo et al., 2023). Ultimately,
493 increasing transparency and providing uncertainty estimates with predictions will be essential for
494 convincing engineers to adopt AI tools widely.

495 **Computational Efficiency:** While many AI models can run predictions in milliseconds once trained,
496 the training process or the integration with large-scale simulations can be computationally demand-
497 ing. Physics-informed models, for example, often require significant computational resources to
498 converge on a solution for complex 3D problems. Future research will likely explore more efficient
499 training algorithms, model compression, and the use of high-performance computing (including
500 GPUs and cloud platforms) to make training and deploying intelligent models more accessible. Ad-
501 ditionally, intelligent algorithms might be used to accelerate each other – for example, using one
502 neural network to intelligently sample or reduce the input space for another, thereby cutting down
503 computation without sacrificing accuracy.

504 **Integration with Domain Workflows:** For AI to truly revolutionize rock engineering, it must be
505 integrated into existing engineering workflows and software. This means AI models should be
506 packaged into user-friendly tools, possibly as add-ons to popular rock engineering software or as
507 stand-alone decision support systems. There is ongoing work on frameworks to guide practitioners
508 in selecting appropriate AI methods for a given problem (Guardiani et al., 2022). Such frameworks
509 help in demystifying AI for engineers by linking problem types (e.g. "classification problem with
510 small dataset") to recommended techniques (e.g. "SVM or decision tree ensemble") (Xu et al.,
511 2023). Education and training of rock engineers in data science fundamentals will also facilitate
512 smoother adoption – the next generation of geotechnical professionals will likely need to be as
513 comfortable using a machine learning model as they are using a Mohr-Coulomb failure criterion.

514 **Maintenance of AI Systems:** Unlike physical laws, data-driven models may need periodic retraining
515 or calibration as new data come in. For instance, as an operation progresses and more monitor-
516 ing data are collected, initial predictive models for deformation or seismicity might need updating
517 to maintain accuracy. Establishing protocols for model maintenance, validation, and update is im-
518 portant so that AI models remain reliable over the lifespan of a project. In addition, ensuring repro-
519 ducibility of AI-based research is a community challenge – sharing code, model parameters, and test
520 datasets openly can help validate findings and prevent situations where a published model cannot be
521 reproduced or trusted in a different context.

522 Looking forward, the future of intelligent rock mechanics appears bright. We anticipate far greater
523 use of hybrid models that combine data-driven learning with explicit physics and domain expertise –
524 this could mean widespread adoption of physics-informed neural networks for routine design prob-
525 lems, or real-time digital twins of underground constructions that marry sensor data with adaptive
526 AI predictions. Advances in related fields such as computer vision, natural language processing,
527 and robotics will also influence rock mechanics. For example, large language models (LLMs) might
528 be harnessed to quickly parse and summarize vast geotechnical reports or to assist in generating
529 computer code for simulations(see Appendix A.4), although their direct role in core rock mechanics
530 analysis remains to be defined. Meanwhile, spatial intelligence – AI that understands spatial and ge-
531 ometric information – will be crucial for interpreting geological models and integrating multi-scale
532 data (from microscopic images to GIS-based regional data) into a coherent predictive framework (Li
533 et al., 2017).

534 7 CONCLUSION

535
536 In conclusion, intelligent rock mechanics is moving from a niche research topic toward mainstream
537 application. The methods reviewed here, from predicting rock properties with simple tests to au-
538 tomating the mapping of fractures and optimizing tunnel operations, showcase a paradigm shift in
539 how we handle the uncertainty and complexity of rock engineering. By addressing current chal-
lenges and fostering interdisciplinary collaboration between AI experts and rock mechanics special-

ists, the next decade should see these intelligent methods mature into standard tools – making rock engineering safer, more efficient, and more innovative than ever before.

A APPENDIX

This Appendix provides supplementary materials that extend the reproducibility and analytical rigor of the review.

A.1 DATASETS OF INTELLIGENT ROCK MECHANICS

This appendix summarizes the major publications, research subjects, and available datasets or codes that were reviewed or referenced in this study. Table 1 provides an overview of representative works across microstructure reconstruction, fracture modeling, mechanical property estimation, and rock engineering applications, along with links to open-source repositories and supplementary materials.

Table 1: Summary of publications, subjects, and available datasets or codes.

| Publications | Subject | Data set |
|----------------------------------|-----------------------------------|-----------------------------|
| (Argilaga et al., 2024) | Microstructure Reconstruction | DOI Link |
| (Lei & Fan, 2024) | Fracture Reconstruction | GitHub Link |
| (Kim et al., 2023) | Fracture Reconstruction | GitHub Link |
| (Abdi et al., 2023) | Mechanical Properties | Appendix A |
| (Afrasiabian & Eftekhari, 2022) | Mechanical Properties | Table 1 |
| (Heidaripannah et al., 2017) | Mechanical Properties | Table 1, Table 2 |
| (Hu et al., 2023b) | Mechanical Properties | Appendix A |
| (Moussas & Diamantis, 2021) | Mechanical Properties | Table 1 |
| (Mozumder & Laskar, 2015) | Mechanical Properties | Appendix B |
| (Narendra et al., 2006) | Mechanical Properties | Table 3, Table 4 |
| (Tiryaki, 2008) | Mechanical Properties | Table 1 |
| (Abueidda & Mobasher, 2024) | Governing Equations | GitHub Link |
| (Behzadafshar et al., 2019) | Governing Equations | GitHub Link |
| (Bai et al., 2023a) | Governing Equations | GitHub Link |
| (Black & Najafi, 2022) | Governing Equations | GitHub Link |
| (Lee et al., 2022) | Rock Mass Classification | GitHub Link |
| (Adoko et al., 2013) | Rockburst | Table 1 |
| (Feng & Jimenez, 2015) | Tunnel Squeezing | Online Link |
| (Ferentinou & Sakellariou, 2007) | Slope | Table 3, Table 5 |
| (Kayabasi et al., 2015) | Slope | Appendix A |
| (Kovacevic et al., 2021) | Tunnelling Deformation | Appendix A |
| (Liang et al., 2021) | Slope | Appendix |
| (Bahtiri et al., 2023) | Coal Mining | Appendix A |
| (Neaupane & Adhikari, 2006) | Tunneling-induced Ground Movement | Table 2, Table 3 |

A.2 CASE STUDY OF MACHINE LEARNING IN ROCKBURST

In the construction of ultra-deep tunnels in the mountainous regions of Southwest China, frequent rockburst disasters represent one of the most severe challenges to construction safety. The combination of high in-situ stress, large burial depth (up to 2 km), and hard granite strata leads to violent dynamic failures during excavation. Traditional rockburst warning approaches—typically based on single empirical indicators or static analyses—cannot adapt to the cyclic “blasting round” rhythm of tunnel excavation. As a result, these methods often exhibit poor timeliness, limited adaptability, and low predictive accuracy.

To overcome these limitations, Hu et al. (2023a) developed a machine-learning-based intelligent early-warning method that utilizes microseismic (MS) information time series, treating each blasting round as a fundamental temporal unit. The proposed framework consists of three main stages:

(i) segmentation of accurate early-warning units synchronized with the blasting cycles, (ii) pre-processing and feature extraction of MS parameters, and (iii) construction of dual long short-term memory (LSTM) models—one for MS parameter prediction and another for rockburst risk classification. This dual-model framework enables the system to issue proactive warnings of rockburst intensity several blasting cycles in advance. Figure 2 illustrates the methodological workflow and corresponding verification results.

Figure 2(a) presents the geological cross-section of the studied tunnel section, which passes through Eocene medium-grained biotite granite (E²R) intersected by faults (F1, F2), jointed zones, and pegmatite veins. The high strength and low permeability of the granite, coupled with localized stress concentrations near faults, create the fundamental geological conditions for rockburst occurrence. This establishes the geological boundary for subsequent monitoring and analysis.

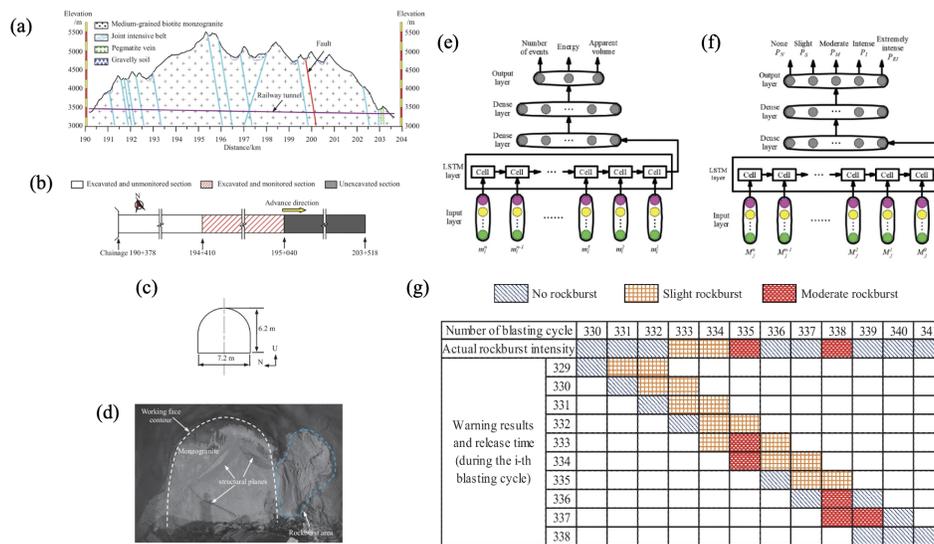


Figure 2: Case study of machine-learning-based intelligent rockburst early warning using microseismic time-series data in an ultra-deep tunnel. (a) Geological cross-section; (b) Excavation and monitoring layout; (c) Tunnel cross-section geometry; (d) Typical excavation face photograph; (e) Microseismic Information Prediction Model (MSIPM); (f) Rockburst Time Warning Model (RBTWM); (g) Comparison between predicted and actual rockburst intensities.

As shown in Figure 2(b), the plan view illustrates the spatial configuration of the microseismic monitoring system relative to the excavation progress. The monitored section (chainage 190+378 to 203+518) is instrumented with eight sensors covering a 35 m radius ahead and 25 m behind the tunnel face, ensuring that all collected MS data correspond to the most active stress disturbance zones. Figure 2(c) provides the standard “city-gate” tunnel cross-section, with a net width of 7.2 m and a height of 6.2 m (equivalent circular diameter 6.6 m). Based on this geometry, the early-warning unit extends five times the equivalent diameter laterally, encompassing all potential zones affected by rockburst events. This geometric definition forms the spatial foundation for data selection and model input consistency.

The field observation shown in Figure 2(d) depicts the excavation face with massive granite blocks, developed joints, and localized spalling pits produced by rockburst. Such visual evidence provides the ground truth for model calibration, directly linking predicted rockburst intensity with observed physical damage patterns.

The architecture of the Microseismic Information Prediction Model (MSIPM), shown in Figure 2(e), is designed to predict short-term trends of MS parameters—including event count, energy ($\times 10^3$ J), and apparent volume ($\times 10^3$ m³). The model employs a 64-unit LSTM hidden layer with dropout (rate 0.1) to capture the temporal dependency inherent in the MS evolution process. It outputs forecasts for one to three future blasting cycles, effectively identifying precursor dynamics that indicate impending rockbursts.

The subsequent Rockburst Time Warning Model (RBTWM), illustrated in Figure 2(f), translates the MSIPM-predicted sequences into probabilistic rockburst warnings. Its input combines both measured and predicted MS data, enriched with derived cumulative and rate-based features. With 112 LSTM units in the hidden layer, the RBTWM outputs the likelihood of three categories—no rockburst, slight rockburst, and moderate rockburst—thus providing cycle-level predictive alerts. The integration of MSIPM and RBTWM constitutes a robust dual-model system that bridges forward MS prediction with real-time risk assessment.

Model validation results, as displayed in Figure 2(g), demonstrate strong agreement between predictions and field observations across 66 blasting cycles. For instance, in cycle 335, the model issued a “moderate rockburst” warning two cycles before the actual event, which was subsequently confirmed by the field-observed spalling pit. The framework achieved a one-cycle-ahead prediction accuracy of 74.6%, confirming its reliability and applicability under real construction conditions.

Overall, this case study demonstrates that temporal deep-learning methods such as LSTM can effectively integrate continuous microseismic monitoring data with the cyclic excavation process. By capturing the temporal evolution of MS activity, the dual-model framework provides a data-driven yet physically interpretable approach for real-time rockburst prediction, advancing intelligent early-warning systems in deep tunnel engineering.

A.3 CASE STUDY OF PHYSICS-INFORMED NEURAL NETWORK IN TUNNEL ENGINEERING

With the rapid expansion of metro and tunnel infrastructure in global megacities, accurately predicting tunnel-induced ground deformation (TIGD) has become essential for ensuring the safety of surrounding structures and surface facilities. Although shield and TBM excavation methods provide advantages such as reduced environmental disturbance and high construction efficiency, complex geotechnical conditions and strict deformation control requirements still pose major engineering challenges. Conventional prediction approaches—including analytical solutions based on idealized assumptions, computationally expensive finite element simulations, costly physical model tests, and spatially limited field monitoring—are often constrained by practicality, computational cost, or data availability, making it difficult to achieve high accuracy under real-world conditions.

To address these challenges, recent advances have introduced *physics-informed neural networks* (PINNs), which embed governing physical laws directly into data-driven learning frameworks. By coupling data learning with physical constraints, PINNs achieve greater interpretability and robustness, especially when dealing with sparse monitoring data. A representative implementation is the Data-Physics-driven Neural Network (DPNN), developed for high-fidelity prediction and inverse identification of soil parameters in complex tunneling environments. Figure 3 presents a case study illustrating the DPNN’s architecture, validation process, and predictive capability (Liu et al., 2024).

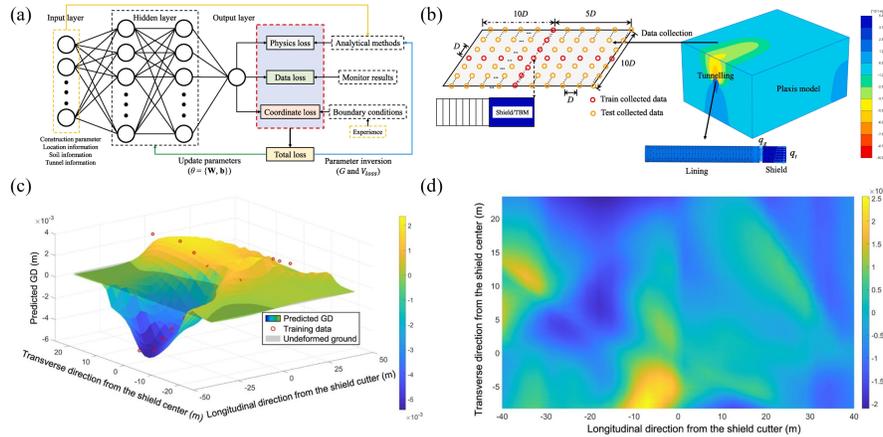
As shown in Figure 3(a), the DPNN architecture integrates four categories of input—construction parameters, spatial coordinates, soil properties, and tunnel geometry—into a unified neural framework. Multiple nonlinear hidden layers capture the complex interactions between these factors to produce deformation predictions. The model is trained through a composite loss function that combines three terms: a data loss minimizing deviations from measured or simulated data, a physics loss enforcing analytical and constitutive relationships, and a coordinate loss maintaining empirical boundary conditions. This hybrid optimization not only improves prediction accuracy but also allows inverse estimation of key geotechnical parameters such as shear modulus and volume loss.

Figure 3(b) shows the numerical model and data acquisition process used for validation. A detailed PLAXIS 3D finite element model of Shanghai soft soil was constructed to provide reference data. From 176 potential monitoring points, a sparse subset of 26 was selected to emulate realistic field conditions with limited data availability. The deformation results from these points were used to train and validate the DPNN, enabling systematic evaluation of its interpolation and generalization capabilities under sparse data scenarios.

In Figure 3(c), the DPNN’s predictive accuracy is compared with conventional machine-learning models such as BPNN, RF, and SVM. The DPNN’s predicted deformation contours and error distributions exhibit excellent agreement with FEM reference results, achieving a coefficient of determination of $R^2 = 0.9145$ and a normalized error of $L_2 = 0.2430$. The inclusion of physical constraints

702 within the learning process significantly enhances prediction stability, suppresses non-physical oscillations, and ensures consistent deformation patterns across heterogeneous soil zones.

705 Finally, Figure 3(d) demonstrates the DPNN’s parameter inversion and deformation characterization capabilities. The inferred soil parameters rapidly converge to their true reference values with minimal residual errors, while the reconstructed longitudinal settlement profile accurately reproduces the characteristic “hump-shaped” deformation pattern induced by shield advancement—a complex feature often missed by traditional analytical models. These results collectively highlight the DPNN’s dual strengths in physically consistent prediction and reliable parameter identification, establishing it as a powerful and data-efficient computational framework for tunnel deformation analysis.



727 Figure 3: Case study of the Data–Physics-driven Neural Network (DPNN) for predicting tunnel-induced ground deformation (TIGD). (a) DPNN architecture; (b) Numerical model and data acquisition; (c) Prediction accuracy and model comparison; (d) Parameter inversion and deformation characteristics.

732 A.4 USAGE OF LLMs FOR ROCK MECHANICS

734 A PYTHON script based on the finite difference method (FDM) was developed to solve the steady-state seepage equation with fixed-head boundaries and an impermeable sheet pile. The program iteratively computes the hydraulic head distribution until convergence. This code was generated and refined with assistance from a LLM (ChatGPT). The full script is available in the Supplementary Materials.

740 Listing 1: Seepage Flow Analysis using Finite Difference Method

```

741 #!/usr/bin/env python3
742 # -*- coding: utf-8 -*-
743
744 import numpy as np
745 import matplotlib.pyplot as plt
746
747 # -----
748 # Seepage Flow Analysis (FDM)
749 # -----
750
751 # Geometric Information
752 H1 = 10.0 # Left water level (m)
753 H2 = 0.0 # Right water level (m)
754 W = 25.0 # Width of soil layer (m)
755 H_soil = 10.0 # Depth of soil layer (m)
756 W_pile = 1.0 # Width of sheet pile (m)
757 D = 5.0 # Depth of sheet pile penetration (m)
758
759 # FDM Settings

```

```

756 dx = 0.1 # Grid size in x-direction (m)
757 dy = 0.1 # Grid size in y-direction (m)
758 threshold = 1e-4 # Convergence threshold
759
760 # Grid Points
761 nx = int(W / dx) + 1 # number of grid points in x
762 ny = int(H_soil / dy) + 1 # number of grid points in y
763
764 # Initialize Water Head Matrix (H): ny rows (y), nx cols (x)
765 H = np.ones((ny, nx)) * ((H1 + H2) / 2.0)
766
767 # Apply Boundary Conditions
768 H[:, 0] = H1 # Left boundary
769 H[:, -1] = H2 # Right boundary
770 H[0, :] = H1 # Top boundary
771 H[-1, :] = H2 # Bottom boundary
772
773 # Sheet pile (no-flow through the pile): keep values fixed in that x-band
774 pile_start = int(round((W/2.0 - W_pile/2.0) / dx)) # zero-based index
775 pile_end = int(round((W/2.0 + W_pile/2.0) / dx)) # inclusive in MATLAB
776 sense
777 H[:, pile_start:pile_end+1] = (H1 + H2) / 2.0
778
779 # Iterative Finite Difference (Laplace: 5-point average with dx=dy)
780 converged = False
781 iteration = 0
782 while not converged:
783     H_old = H.copy()
784
785     for j in range(1, ny - 1): # y-direction (rows)
786         for i in range(1, nx - 1): # x-direction (cols)
787             if not (pile_start <= i <= pile_end):
788                 H[j, i] = 0.25 * (H_old[j+1, i] + H_old[j-1, i] +
789                     H_old[j, i+1] + H_old[j, i-1])
790
791     H[:, 0] = H1
792     H[:, -1] = H2
793     H[0, :] = H1
794     H[-1, :] = H2
795
796     H[:, pile_start:pile_end+1] = (H1 + H2) / 2.0
797
798     max_diff = np.max(np.abs(H - H_old))
799     iteration += 1
800     if max_diff < threshold:
801         converged = True
802
803 print(f"Converged in {iteration} iterations, max_diff={max_diff:.6e}")
804
805 # Plot the Water Head Distribution
806 x = np.linspace(0.0, W, nx)
807 y = np.linspace(0.0, H_soil, ny)
808 X, Y = np.meshgrid(x, y)
809
810 plt.figure(figsize=(7, 4.8))
811
812 cf = plt.contourf(X, Y, H, levels=20)
813 plt.colorbar(cf, label='Head (m)')
814 plt.xlabel('X (m)')
815 plt.ylabel('Y (m)')
816 plt.title('Water Head Distribution in Soil Layer (FDM)')
817 plt.tight_layout()
818 plt.show()
819

```

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